# SOLUTION FOR TWO-POINT BOUNDARY VALUE PROBLEM OF THE SEMILINEAR FRACTIONAL DIFFERENTIAL EQUATION* ${ }^{*}$ 

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#### Abstract

In this paper, we establish the existence result of solution and positive solution for two-point boundary value problem of a semilinear fractional differential equation by using the Leray-Schauder fixed-point theorem. The discussion is based on the system of integral equations on a bounded region.

Keywords boundary value problem; Green's function; Leray-Schauder fixed point theorem; system of integral equations


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## 1 Introduction

Fractional differential equations have received increasing attention during the past decades. It has attracted a lot of attention of researchers to promote the continuous development of methods, theories and applications in the field of small area estimation (see [1-3]). Fractional derivative is divided into two categories: standard Riemann-Liouville derivative and Caputo fractional derivative.

The aim of this paper is to study the existence result of solution and positive solution for the following two-point boundary value problem of the semilinear fractional differential equation

$$
\left\{\begin{array}{l}
D^{\alpha} u(t)+f\left(t, u(t), D^{\alpha-1} u(t)\right)=0, \quad 0 \leqslant t \leqslant 1,  \tag{1.1}\\
u(0)=0, \quad u(1)=B, \quad D^{\alpha-1} u(0)=C,
\end{array}\right.
$$

where $2<\alpha \leqslant 3$ and $A, B, C$ are real numbers, $D^{\alpha}$ is the standard RiemannLiouville derivative, and $f:[0,1] \times \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$ is continuous on its domain. Such a

[^0]nonlinearity term $f\left(t, u(t), D^{\alpha-1} u(t)\right)$ has been studied widely in [6,7]. In [6], by means of the Schauder fixed point theorem and the Banach contraction principle the authors investigated the existence and uniqueness of solutions for a class of nonlinear multi-point boundary value problems for fractional differential equations
\[

\left\{$$
\begin{array}{l}
D^{\alpha} u(t)+f\left(t, u(t), D^{\beta} u(t)\right)=0, \quad 0 \leqslant t \leqslant 1, \\
u(0)=0, \quad D^{\beta} u(1)-\sum_{i=1}^{m-2} \xi_{i} D^{\beta} u\left(\xi_{i}\right)=u_{0} .
\end{array}
$$\right.
\]

In [7], by means of a fixed point theorem on a cone, the authors investigated the existence of positive solutions for the following singular fractional boundary value problem

$$
\left\{\begin{array}{l}
D^{\alpha} u(t)+f\left(t, u(t), D^{\mu} u(t)\right)=0, \quad 0 \leqslant t \leqslant 1, \\
u(0)=u(1)=0 .
\end{array}\right.
$$

The difference between [6] and [7], the system of integral equations is adopted skillfully in this paper. In the literature of $[8], A=0$ is the special case of this paper.

## 2 Preliminaries

For convenience, we present here the necessary definitions and some lemmas from fractional calculus theory.

Definition 2.1 ${ }^{[4]}$ The Riemann-Liouville fractional integral of order $\alpha>0$ of a function $f:(0, \infty) \rightarrow \mathbb{R}$ is given by

$$
I_{0^{+}}^{\alpha} f(t)=\frac{1}{\Gamma(\alpha)} \int_{0}^{t}(t-s)^{\alpha-1} f(s) \mathrm{d} s
$$

provided the right side is pointwise defined on $(0, \infty)$.
Definition 2.2 ${ }^{[4]}$ The Riemann-Liouville fractional derivative of order $\alpha>0$ of a continuous function $f:(0, \infty) \rightarrow \mathbb{R}$ is given by

$$
D_{0^{+}}^{\alpha} f(t)=\frac{1}{\Gamma(n-\alpha)}\left(\frac{\mathrm{d}}{\mathrm{~d} t}\right)^{n} \int_{0}^{t} \frac{f(s)}{(t-s)^{\alpha-n+1}} \mathrm{~d} s
$$

where $n=[\alpha]+1,[\alpha]$ denotes the integer part of the real number $\alpha$, provided the right side integral is pointwise defined on $[0,1)$.

Lemma 2.1 ${ }^{[4]}$ Let $\alpha>0$. If we assume $u \in C(0,1) \cap L(0,1)$, then the fractional differential equation

$$
D_{0^{+}}^{\alpha} u(t)=0
$$

has $u(t)=C_{1} t^{\alpha-1}+C_{2} t^{\alpha-2}+\cdots+C_{N} t^{\alpha-N}, C_{i} \in \mathbb{R}, i=1,2, \cdots, N$, which is a unique solution, where $N$ is the smallest integer greater than or equal to $\alpha$.

Lemma 2.2 ${ }^{[4]}$ Assume that $u \in C(0,1) \cap L(0,1)$ with a fractional derivative of order $\alpha>0$ that belongs to $C(0,1) \cap L(0,1)$. Then

$$
I_{0^{+}}^{\alpha} D_{0^{+}}^{\alpha} u(t)=u(t)+C_{1} t^{\alpha-1}+C_{2} t^{\alpha-2}+\cdots+C_{N} t^{\alpha-N}
$$

for some $C_{i} \in \mathbb{R}, i=1,2, \cdots, N$, where $N$ is the smallest integer greater than or equal to $\alpha$.

Property 2.1 ${ }^{[4]}$ Let $\alpha \geqslant 0, m \in \mathbb{N}$ and $D=\frac{\mathrm{d}}{\mathrm{d} x}$. If the fractional derivatives $\left(D_{0^{+}}^{\alpha} y\right)(x)$ and $\left(D_{0^{+}}^{\alpha+m} y\right)(x)$ exist, then

$$
\left(D^{m} D_{0^{+}}^{\alpha} y\right)(x)=\left(D_{0^{+}}^{\alpha+m} y\right)(x)
$$

Lemma 2.3 Let $f:[0,1] \times \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$ be a given function. Then the boundary value problem

$$
\left\{\begin{array}{l}
D^{\alpha} u(t)+f\left(t, u(t), D^{\alpha-1} u(t)\right)=0, \quad 0 \leqslant t \leqslant 1,  \tag{2.1}\\
u(0)=0, \quad u(1)=B, \quad D^{\alpha-1} u(0)=C
\end{array}\right.
$$

is equivalent to the system of integral equations

$$
\left\{\begin{array}{l}
v(t)=C-\int_{0}^{t} f(s, u(s), v(s)) \mathrm{d} s  \tag{2.2}\\
u(t)=B t^{\beta-1}-\int_{0}^{1} G(t, s) v(s) \mathrm{d} s
\end{array}\right.
$$

where

$$
G(t, s)= \begin{cases}\frac{[t(1-s)]^{\beta-1}-(t-s)^{\beta-1}}{\Gamma(\beta)}, & s \leqslant t \\ \frac{[t(1-s)]^{\beta-1}}{\Gamma(\beta)}, & t \leqslant s .\end{cases}
$$

Here $G(t, s)$ is called the Green function of boundary value problem (2.1), $\beta=\alpha-1$.
Proof Let $v(t)=D^{\alpha-1} u(t)$. Then problem (2.1) is equivalent to the system of ordinary differential equations

$$
\left\{\begin{array}{l}
D^{\alpha-1} u(t)=v(t), \quad 0 \leqslant t \leqslant 1,2<\alpha \leqslant 3,  \tag{2.3}\\
v^{\prime}(t)=-f(t, u(t), v(t)), \\
u(0)=0, \quad u(1)=B, \quad v(0)=C .
\end{array}\right.
$$

Let $\beta=\alpha-1,1<\beta \leqslant 2$. Then problem (2.3) is equivalent to the system of ordinary differential equations

$$
\left\{\begin{array}{l}
D^{\beta} u(t)=v(t), \quad 0 \leqslant t \leqslant 1,2<\alpha \leqslant 3, \\
v^{\prime}(t)=-f(t, u(t), v(t)) \\
u(0)=0, \quad u(1)=B, \quad v(0)=C
\end{array}\right.
$$

We find that

$$
\begin{gathered}
v(t)=C-\int_{0}^{t} f(s, u(s), v(s)) \mathrm{d} s \\
u(t)=I^{\beta} v(t)+C_{1} t^{\beta-1}+C_{2} t^{\beta-2}=\frac{1}{\Gamma(\beta)} \int_{0}^{t}(t-s)^{\beta-1} v(s) \mathrm{d} s+C_{1} t^{\beta-1}+C_{2} t^{\beta-2} .
\end{gathered}
$$

On the one hand, the boundary condition $u(0)=0$ implies that $C_{2}=0$.
On the other hand, by applying boundary condition $u(1)=B$, we find that

$$
B=\frac{1}{\Gamma(\beta)} \int_{0}^{1}(1-s)^{\beta-1} v(s) \mathrm{d} s+C_{1},
$$

so it implies that

$$
C_{1}=B-\frac{1}{\Gamma(\beta)} \int_{0}^{1}(1-s)^{\beta-1} v(s) \mathrm{d} s .
$$

Consequently,

$$
\begin{aligned}
v(t) & =C-\int_{0}^{t} f(s, u(s), v(s)) \mathrm{d} s \\
u(t) & =B t^{\beta-1}-\left[\int_{0}^{1} \frac{(1-s)^{\beta-1} t^{\beta-1}}{\Gamma(\beta)} v(s) \mathrm{d} s-\int_{0}^{t} \frac{(t-s)^{\beta-1}}{\Gamma(\beta)} v(s) \mathrm{d} s\right] \\
& =B t^{\beta-1}-\left[\int_{0}^{t} \frac{[t(1-s)]^{\beta-1}-(t-s)^{\beta-1}}{\Gamma(\beta)} v(s) \mathrm{d} s+\int_{t}^{1} \frac{[t(1-s)]^{\beta-1}}{\Gamma(\beta)} v(s) \mathrm{d} s\right] \\
& =B t^{\beta-1}-\int_{0}^{1} G(t, s) v(s) \mathrm{d} s .
\end{aligned}
$$

Lemma 2.4 ${ }^{[5]}$ The function $G(t, s)$ defined by Lemma 2.3 satisfies:
(1) $G(t, s)>0, \quad t, s \in(0,1)$;
(2) there exists a positive function $\gamma \in C(0,1)$ such that

$$
\min _{\frac{1}{4} \leqslant t \leqslant \frac{3}{4}} G(t, s) \geqslant \gamma(s) \max _{0 \leqslant t \leqslant 1} G(t, s)=\gamma(s) G(s, s), \quad \text { for } 0<s<1 \text {. }
$$

## 3 Main Results and Proofs

Let $C[0,1]$ be the Banach space endowed with the max norm $\|u\|=\max _{0 \leqslant t \leqslant 1}|u(t)|$ and $\eta=\max \{|B|,|C|\}$,

$$
\begin{gathered}
T_{1}(u, v)(t)=B t^{\beta-1}-\int_{0}^{1} G(t, s) v(s) \mathrm{d} s, \\
T_{2}(u, v)(t)=C-\int_{0}^{t} f(s, u(s), v(s)) \mathrm{d} s, \\
(T(u, v))=\left(T_{1}(u, v), T_{2}(u, v)\right) .
\end{gathered}
$$

Then, problem (2.2) is equivalent to the following equation

$$
\begin{equation*}
T(u, v)=(u, v), \quad(u, v) \in C[0,1] \times C[0,1] . \tag{3.1}
\end{equation*}
$$

That is, every solution of (2.2) is also a fixed-point of (3.1).
Theorem 3.1 Suppose that $f:[0,1] \times R \times R \rightarrow R$ holds. If there exist $d>0$ and $\frac{1}{2} \leqslant k \leqslant \frac{1}{2 m}$, with $m=\int_{0}^{1} G(s, s) \mathrm{d} s$ such that

$$
\begin{equation*}
\max \{|f(t, u, v)|: t \in[0,1],|u| \leqslant 2 \eta+d,|v| \leqslant k(2 \eta+d)\} \leqslant(2 k-1) \eta+k d . \tag{3.2}
\end{equation*}
$$

Then, problem (1.1) has at least one solution $u^{*} \in C[0,1]$ satisfying $\left\|u^{*}\right\| \leqslant 2 \eta+d$ and $\left\|D^{\alpha-1} u^{*}\right\| \leqslant k(2 \eta+d)$.

Proof Let $C[0,1] \times C[0,1]$ be the Banach space endowed with the norm $\|(u, v)\|=$ $\max \left\{\|u\|, \frac{\|v\|}{k}\right\}, R=2 \eta+d, V_{R}=\{(u, v) \in C[0,1] \times C[0,1]:\|(u, v)\| \leqslant R\}$. Then $V_{R}$ is a convex closed set in $C[0,1] \times C[0,1]$. If $(u, v) \in V_{R}$, then $\|u\| \leqslant R$, and $\|v\| \leqslant k R$. So $|u(t)| \leqslant R,|v(t)| \leqslant k R, 0 \leqslant t \leqslant 1$. By the condition (3.2) of Theorem 3.1, we obtain $|f(t, u, v)| \leqslant(2 k-1) \eta+k d, 0 \leqslant t \leqslant 1$. Thus

$$
\begin{aligned}
\left\|T_{1}(u, v)\right\| & \leqslant \max _{0 \leqslant t \leqslant 1}\left|B t^{\beta-1}\right|+\max _{0 \leqslant t \leqslant 1} \int_{0}^{1} G(t, s)|v(s)| \mathrm{d} s \\
& \leqslant \eta+k R \int_{0}^{1} G(s, s) \mathrm{d} s=(1+2 k m) \eta+k m d, \\
\left\|T_{2}(u, v)\right\| & \leqslant \max _{0 \leqslant t \leqslant 1}|C|+\max _{0 \leqslant t \leqslant 1} \int_{0}^{t}|f(s, u(s), v(s))| \mathrm{d} s \\
& \leqslant \eta+(2 k-1) \eta+k d=2 k \eta+k d .
\end{aligned}
$$

In view of the above, we see that

$$
\begin{aligned}
\left\|\left(T_{1}(u, v), T_{2}(u, v)\right)\right\| & =\max \left\{\left\|T_{1}(u, v)\right\|, \frac{1}{k}\left\|T_{2}(u, v)\right\|\right\} \\
& \leqslant \max \{(1+2 k m) \eta+k m d, 2 \eta+d\}=2 \eta+d .
\end{aligned}
$$

Therefore, $T: V_{R} \rightarrow V_{R}$. Then, we can easily prove that $T: C[0,1] \times C[0,1] \rightarrow$ $C[0,1] \times C[0,1]$ is completely continuous by Arzela-Ascoli theorem. Therefore, according to Leray-Schauder fixed-point theorem, the operator $T$ has a fixed point $\left(u^{*}, v^{*}\right) \in V_{R}$.

Theorem 3.2 Suppose that $B \geqslant 0, C \leqslant 0$ and $f:[0,1] \times R_{+} \times R_{-} \rightarrow R_{+}$. If there exist $d>0$ and $\frac{1}{2} \leqslant k \leqslant \frac{1}{2 m}$, with $m=\int_{0}^{1} G(s, s) \mathrm{d}$ s such that

$$
\max \{f(t, u, v): t \in[0,1], 0 \leqslant u \leqslant 2 \eta+d,-k(2 \eta+d) \leqslant v \leqslant 0\} \leqslant(2 k-1) \eta+k d .
$$

Then, problem (1.1) has at least one solution $u^{*} \in C[0,1]$ satisfying $\left\|u^{*}\right\| \leqslant 2 \eta+d$ and $\left\|D^{\alpha-1} u^{*}\right\| \leqslant k(2 \eta+d)$.

Proof Set

$$
\begin{aligned}
f_{1}(t, u, v) & = \begin{cases}f(t, u, v), & (t, u, v) \in[0,1] \times R_{+} \times R_{-}, \\
f(t, u, 0), & (t, u, v) \in[0,1] \times R_{+} \times R_{+},\end{cases} \\
f_{2}(t, u, v) & = \begin{cases}f_{1}(t, u, v), & (t, u, v) \in[0,1] \times R_{+} \times R \\
f_{1}(t, 0, v), & (t, u, v) \in[0,1] \times R_{-} \times R\end{cases}
\end{aligned}
$$

Obviously, $f_{2}:[0,1] \times R \times R \rightarrow R_{+}$is continuous and

$$
\begin{aligned}
& \max \left\{\left|f_{2}(t, u, v)\right|: t \in[0,1],|u| \leqslant 2 \eta+d,|v| \leqslant k(2 \eta+d)\right\} \\
= & \max \{f(t, u, v): t \in[0,1], 0 \leqslant u \leqslant 2 \eta+d,-k(2 \eta+d) \leqslant v \leqslant 0\} \\
\leqslant & (2 k-1) \eta+k d .
\end{aligned}
$$

Applying Theorem 3.1, the problem

$$
\left\{\begin{array}{l}
D^{\alpha} u(t)+f_{2}\left(t, u(t), D^{\alpha-1} u(t)\right)=0, \quad 0 \leqslant t \leqslant 1, \\
u(0)=0, \quad u(1)=B, \quad D^{\alpha-1} u(0)=C
\end{array}\right.
$$

has at least one solution $u^{*} \in C[0,1]$ satisfying $\left\|u^{*}\right\| \leqslant 2 \eta+d$ and $\left\|D^{\alpha-1} u^{*}\right\| \leqslant$ $k(2 \eta+d)$.

If $C \leqslant 0$, then

$$
\begin{equation*}
D^{\alpha-1} u^{*}(t)=C-\int_{0}^{t} f_{2}\left(s, u^{*}(s), D^{\alpha-1} u^{*}(s)\right) \mathrm{d} s \leqslant 0, \quad 0 \leqslant t \leqslant 1 . \tag{3.3}
\end{equation*}
$$

Consider that

$$
\begin{equation*}
u^{*}(t)=B t^{\beta-1}-\int_{0}^{1} G(t, s) D^{\alpha-1} u^{*}(s) \mathrm{d} s \geqslant 0, \quad 0 \leqslant t \leqslant 1 . \tag{3.4}
\end{equation*}
$$

From (3.3) and (3.4), we get

$$
f_{2}\left(s, u^{*}(s), D^{\alpha-1} u^{*}(s)\right)=f\left(s, u^{*}(s), D^{\alpha-1} u^{*}(s)\right) .
$$

This proves that $u^{*}$ is a solution of problem (1.1).
If $C<0$, then

$$
u^{*}(t)=B t^{\beta-1}-\int_{0}^{1} G(t, s) D^{\alpha-1} u^{*}(s) \mathrm{d} s>0, \quad 0 \leqslant t \leqslant 1 .
$$

If $B=C=0$ and $f(t, 0,0) \neq 0,0 \leqslant t \leqslant 1$, then the zero function is not a solution of problem (1.1).

## 4 Example

Consider the following boundary value problem

$$
\left\{\begin{array}{l}
D^{\frac{5}{2}} u(t)+\left(k-\frac{1}{2}\right) t^{2} u+\sin D^{\frac{3}{2}} u(t)=0, \quad 0 \leqslant t \leqslant 1,  \tag{4.1}\\
u(0)=0, \quad u(1)=B, \quad D^{\frac{3}{2}} u(0)=C .
\end{array}\right.
$$

Let $D^{\frac{3}{2}} u(t)=v(t), R=2 \eta+d, d>2$. If $(u, v) \in V_{R}$, then $\|u\| \leqslant R$, and $\|v\| \leqslant k R$. We have

$$
|f(t, u, v)|=\left|\left(k-\frac{1}{2}\right) t^{2} u+\sin v(t)\right| \leqslant\left(k-\frac{1}{2}\right)(2 \eta+d)+1 \leqslant(2 k-1) \eta+k d .
$$

Therefore,

$$
\max \{|f(t, u, v)|: t \in[0,1],|u| \leqslant 2 \eta+d,|v| \leqslant k(2 \eta+d)\} \leqslant(2 k-1) \eta+k d
$$

Then by Theorem 3.1, the boundary value problem (4.1) has at least one solution $u^{*} \in C[0,1]$ satisfying $\left\|u^{*}\right\| \leqslant 2 \eta+d$ and $\left\|D^{\frac{3}{2}} u^{*}\right\| \leqslant k(2 \eta+d)$.

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